Thank you for the trust you have placed in me by using these IFR notes.

The notes include only summarised knowledge for the IR Ground Component, and are not intended as an IREX study guide. Previous knowledge is required for these notes to be useful, and they are meant to be a compressed revision guide for your flight test or proficiency check. They would also be useful for IFR revision for a job interview.

I have also included a few paragraphs on PBN, RNP, GNSS, and ADS-B for those nervous about new technology questions on their next IPC.

Hopefully this guide will help you connect the dots, but if instead it uncovers knowledge gaps, make sure to reference the AIP/CASR/MOS and it will all come back.

This guide has been compiled by a Flight Examiner with years of experience teaching IFR, but if you have any feedback please email me any concerns or suggestions. This document will undeniably improve with time.

Disclaimer: This document is an academic reference tool only and is not to be used operationally. Always refer to CAR, CASR, CAO, CAAP, AIP, DAP, ERSA, and Company Operations Manuals. The author does not guarantee the accuracy or currency of any information provided. Please check back regularly for updated versions.

“A good pilot is one who uses superior judgement to avoid those situations where they might have to use their superior skills”

David Roses
david@flighttest.net
1. GROUND COMPONENT – KNOWLEDGE REQUIREMENTS MOS Schedule 5 Appendix M.1 (page 601, p624)

- Privileges and limitations of the rating
- Proficiency check requirements
- IFR and approach recency requirements
- Night recency requirements *
- Night VFR operations *
- Aircraft instrument requirements
- Interpreting operational and meteorological information
- Take-off minima
- Holding and alternate requirements
- IFR procedures for all airspace requirements
- Departure and approach instrument procedures
- Operations below LSALT and MSA for day and night operations
- GNSS and PBN standards
- Circling approaches
- Adverse weather operations
- ERSA normal and emergency procedures
- IFR planning

*Only appears as required knowledge for initial issue flight test, but should be considered essential knowledge.


Fly as PIC of a ME or SE aeroplane under the IFR and NVFR, as long as IPC is current and the relevant recency requirements are met.

Can only conduct a circling approach if last IPC included a circling approach.

IPC expires last day of month +12 months. Can do an IPC up to 3 months before expiry and still conserve original expiry date for following year.

IPC in a single covers you for SEA AFR (24 months). IPC in a twin covers you for MEA&SEA AFR (24 months).

A Part 135 operation under the IFR or NVFR must be conducted in a MEA or prescribed SEA aeroplane.

IFR Recency
3 instrument approaches in the last 90 days.
1 approach in last 90 days covering required approach type (2D or 3D / CDI or AZI).

Note: The approaches can be in IMC, VMC or in an FSTD.

A pilot who has passed an IFR OPC in the previous 3 months is taken to meet the IAP recency requirements.

Single pilot recency:
A single pilot IFR flight of 1h duration, which included 1 instrument approach, in last 6 months.

Night IFR recency:
Nil. If carrying PAX, 3 TOL at night in 90 days.

Night VFR recency:
N/A, you can pilot a flight under the NVFR if your IR is current and recent. If PAX, 3 TOL at night in 90 days.

CASR 135.380.2d: The pilot, or at least one of the pilots, of a Part 135 operation carrying passengers under the Night VFR must hold an instrument rating.
3. EQUIPMENT FOR PART 135 SINGLE PILOT IFR OPERATION  
PART 135 MOS11.07–11.28, PART 91 MOS 10.04

Airspeed indicator  
Pressure altimeter x2  
Compass  
Clock or watch  
Turn (unless Al x3) and slip indicator  
Attitude indicator x2 with alternate power supply  
Vertical speed indicator  
Direction indicator with alternate power supply  
Outside air temperature  
Assigned altitude indicator, for flight in CTA

Pitot heat  
Alternate static or two balanced flush static ports  
Means of monitoring power supply to gyroscopic instruments, if any  
The second attitude indicator must continue to work for at least 30 minutes following an electrical failure  
*Altimeter must be accurate to +/-60ft. Can depart if +/-75ft but check at next landing point must be +/-60ft.

2 GNSS (TSO C145, C146, C196) or 1 GNSS (at least TSO C129) and 1 VOR or 1 ADF  
The navigation equipment fitted to an aeroplane must be such that, in the event of the failure of any navigation equipment at any stage of a flight, sufficient navigation equipment remains to enable the aeroplane to navigate in accordance with the aeroplane’s operational flight plan and the requirements of ATS.

Means of illuminating instruments with standby power and intensity control  
Pilot compartment lighting for reading maps and documents  
Lighting in all passenger compartments  
Nav lights, anti-collision lights (beacon and/or strobes)  
Two landing lights, or one landing light with two bulbs or filaments  
Portable torch for each crew member

Autopilot with heading and altitude hold capability. An autopilot can be U/S for flights conducted in VMC by day.  
-Pressurised turbine powered aeroplanes or other aeroplanes operating in controlled airspace above FL150 must be fitted with an altitude alerting system.  
-Pressurised turbine aircraft or piston aircraft above 5700 which are required to be crewed by two pilots, carrying pax (or aeromedical) must be fitted with a weather radar.  
-Aeroplanes >5700Kg carrying pax (or aeromedical) must be fitted with GPWS (or TAWS <5700Kg).

Instruments required for a Part 135 NVFR flight can be found in Part 135 MOS 11.06

4. INSTRUMENT ERRORS & MALFUNCTIONS

Know the location of the alternate static source “knob” on your aeroplane.

<table>
<thead>
<tr>
<th></th>
<th>Pitot blocked, climbing</th>
<th>Pitot blocked, desc</th>
<th>Static blocked, climbing</th>
<th>Static blocked, desc</th>
</tr>
</thead>
<tbody>
<tr>
<td>Altimeter</td>
<td>-</td>
<td>-</td>
<td>Reading frozen</td>
<td>Reading frozen</td>
</tr>
<tr>
<td>VSI</td>
<td>-</td>
<td>-</td>
<td>Returns to 0 fpm</td>
<td>Returns to 0 fpm</td>
</tr>
<tr>
<td>ASI</td>
<td>ASI no longer reads IAS, but reflects the behaviour of the altimeter, therefore reading increases</td>
<td>ASI no longer reads IAS, but reflects the behaviour of the altimeter, therefore reading decreases</td>
<td>Underreads</td>
<td>Overreads</td>
</tr>
</tbody>
</table>
5. COMPASS ERRORS

>Acceleration errors “SAND”:
Compass shows apparent turn to the **South** when **Accelerating**, and an apparent turn to the **North** when **Decelerating**. The effect is largest on Easterly and Westerly headings, nil on North and South.

>Turning errors “ONUS”:
To roll out on correct heading, we must **Overshoot** a turn onto a **Northerly** heading and we must **Undershoot** a turn onto a **Southerly** heading. By how much? On North and South, about 30° at lower latitudes (eg. Sydney) and about 15° at higher latitudes (eg. Darwin). On East and West, roll out on the desired heading without correction.

6. TAKEOFF MINIMA **PART 91 MOS 15.03**, **CASR 135.180**

Vis 2000M, Ceiling 300FT.
- With an engine failure at any time after V1, terrain clearance must be assured until reaching LSALT or MSA.
- If a return to land at the departure aerodrome will be necessary in the event of an engine failure, the meteorological conditions must be at or above instrument approach landing minima for the aerodrome or such as to allow a visual approach.
- If a return to the departure aerodrome is not possible, the aeroplane’s performance and fuel availability are each adequate to enable the aeroplane to proceed to a suitable aerodrome, having regard to terrain, obstacles and route distance limitations. The takeoff alternate must be within 1h flight time at OEI speed, and the forecast for the takeoff alternate must indicate that a landing will be possible for up to 1h after departure.

Qualifying multi-engine aeroplanes AIP ENR 1.5 p4.3
2 crew, or 1 crew jet, or 1 crew with autofeather

>5700Kg and is able to meet obstacle clearance reqs in CAO 20.7.1B
≤5700Kg
- gross OEI climb gradient at least 1.9% with OEI
- OEI climb gradient at least 0.3% greater than obstacle free gradient for runway length reqd
- obstacle gradient surveyed out to 7500m from 150m baseline from end of TODA and 12.5% splays. 150m strips always have this.

Ceiling zero feet
Visibility 800m, or;
Visibility 550m
- by day OCTA, day or night in CTR with ATC
- edge lighting ≤60m and centreline markings or lights
- SBY PWR with 1sec switchover time on edge lights, or centreline lights if no edge lights

7. FORECASTS **CAR 239**, **ENR 1.10 p10.7.2**, **PART 91 MOS 7&8**

Before beginning an IFR flight, the pilot in command shall study all available information appropriate to the intended operation (weather forecasts and reports, NOTAMs incl. FIR NOTAMs, airways facilities, and ATC rules appertaining to the particular flight) for the route flown and any aerodromes to be used.

*INTER, TEMPO, FROM weather phenomena that introduce an operational requirement are taken to begin 30 minutes before the time specified on the TAF (ie bad wx on TAFs always extends 30 minutes into the good wx)

*INTER, TEMPO, FROM weather phenomena that remove an operational requirement are taken to begin 30 minutes after the time specified on the TAF (ie bad wx on TAFs always extends 30 minutes into the good wx)

TAF3 are issued every 3 hours and also receive proactive amendments.
Due to increased accuracy, the 30 minute *buffers do not apply during the first 3 hours of a TAF3. Also any PROB30 or PROB40 for TS or reduction of visibility need not be considered.
8. ALTERNATE REQUIREMENTS

ALTERNATES  NavAids, see paragraph #9

COULD     Clouds, see paragraph #9

VERY     Visibility, see paragraph #9

WELL     Wind – crosswind or downwind on runway exceeding the aeroplane’s limitations

PROVE     Provisional forecast, or Probability (PROB) of any adverse conditions (see “Savers” below)

LIFE     Lights, see paragraph #10

SAVERS     Storms, thunderstorms, icing, fog, smoke, cyclones, dust storms, or any other forecasted wx phenomena that would impede a safe landing at the destination aerodrome.

Note: An “Operational Requirement” means the need to plan for an alternate aerodrome or holding fuel.

9. ALTERNATE REQUIREMENTS – NAVAIDS & WEATHER

IFR CHTR/RPT:

The aeroplane should be equipped with two separate receivers (ADF, VOR/ILS, GNSS) that are both capable of conducting an instrument approach that is available at the destination.

Note: If a TSO C129 GNSS is used and an alternate is required: 1. Navigation to the alternate should be accomplished by ground-based navaids, and 2. The alternate should have a suitable approach that uses ground-based navaids or the weather must be suitable for a visual approach.

Aerodrome with instrument approach by day/night with valid TAF: Ceiling and visibility as printed on IAP chart

Aerodrome with instrument approach by day/night but no TAF available: Alternate required!

No instrument approach by day: No more than SCT cloud below last leg LSALT + 500ft and 8Km visibility.

No instrument approach at night: Alternate required.

Note: If an aerodrome has a particular navaid but the pilot or aircraft is not capable of using it, for the purposes of that flight, the aerodrome is taken to not have that navaid.

Night VFR: No more than SCT below 1,500’ AAL and 8Km Vis.

Need to be able to navigate to the destination by means of NDB, VOR, or GNSS.

For NVFR, whether an aerodrome has instrument approaches available or not is irrelevant. We need to be able to navigate to the aerodrome by means of a navaid or GPS, or plan for an alternate within 1 hour’s flight time.

Note: Vertical Visibility is equivalent to overcast cloud at the specified ceiling (eg. VV010 = OVC010).

10. ALTERNATE REQUIREMENTS – DESTINATION RUNWAY LIGHTING

-If lighting is PAL, a responsible person to be on standby to manually turn on the lights should the system fail.
-If lighting is electrically powered there needs to be standby power to automatically engage in the event of a power outage, or alternatively have a responsible person with portable lighting in attendance.
-The alternate requirement need not be applied if carrying holding fuel for first light +10 minutes.

<table>
<thead>
<tr>
<th>PAL SBY PWR</th>
<th>PAL Responsible Person</th>
<th>Electrical (non-PAL) SBY PWR</th>
<th>Electrical (non-PAL) Responsible Person</th>
<th>Portable Responsible Person</th>
</tr>
</thead>
<tbody>
<tr>
<td>Responsible Person</td>
<td>Portable Lighting</td>
<td>Portable Lighting</td>
<td>Portable Lighting</td>
<td>= No Altn Reqd</td>
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<tr>
<td>= No Altn Reqd</td>
<td>= No Altn Reqd</td>
<td>= No Altn Reqd</td>
<td>= No Altn Reqd</td>
<td>= No Altn Reqd</td>
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</tbody>
</table>
If runway lighting not pilot activated, arrangements for 10 minutes before and 30 minutes after takeoff.
30 minutes before arrival until completion of taxi.

If you require an alternate due to lighting, the ALTERNATE does not require SBY PWR.
If you require an alternate due to lighting and the alternate has PAL, you do not require a responsible person in attendance if you have a) 2xVHF receivers, or b) VHF+HF+30min holding fuel.5

11. SPECIAL ALTERNATE MINIMA (DOUBLE ASTERISK ON ILS CHARTS) ENR 1.5 p6.2, PART 91 MOS 8.08
Duplicated VOR/LOC/GP receivers and any combination of two DME or GNSS. ATC at the aerodrome (ie. tower open) and METAR/SPECI service needs to be available (ie check NOTAM).

12. ADVERSE WEATHER FORECAST RECEIVED AFTER DEPARTURE CASR 135.90
For a flight where a destination alternate did not need to be planned, if the pilot in flight receives a weather forecast that indicates that an alternate should have been planned, and if the aeroplane is not carrying sufficient fuel to allow for the new operational requirement, then the flight may not be continued to the planned destination.
However if the mentioned adverse weather forecast is received within 30 minutes of the ETA, the flight may continue to the planned destination, but only if the forecast indicates that the weather at the destination is above the landing minima.

13. DEPARTURE ENR 1.1 P2.7.3, ENR 1.5 p4.4.3, p4.4.4
Unless instructed by ATC or tracking via a SID, be established on the departure track within 5NM.
When not departing via a SID, terrain clearance is always pilot responsibility. Terrain clearance must be assured until reaching LSALT or departure aerodrome MSA, including in the event of an engine failure (MEA).

14. OBSTACLE CLEARANCE ENR 1.5 p8.1.4, p1.10, p2.2, p2.5.2
SID: must climb at minimum 3.3% (including OEI) or as specified on the chart.
MAP: must climb at minimum 2.5% (including OEI). Provides 100ft obstacle clearance. If unable, raise MDA/DA MSA: provides 1000ft obstacle clearance.

15. AIRSPACE ENR 1.4 p4, ENR 1.2 p2, ENR 1.6 p7.1.4, PART 91 MOS 26.69

<table>
<thead>
<tr>
<th>VFR FLIGHTS</th>
<th>XPRD</th>
<th>VHF</th>
<th>CLEARANCE</th>
<th>SEPARATION</th>
<th>VIS</th>
<th>CLOUD SEP</th>
</tr>
</thead>
<tbody>
<tr>
<td>G</td>
<td>No</td>
<td>Above 5000’ and at CTAF where carriage of radio is reqd.</td>
<td>No</td>
<td>Info only</td>
<td>5000m^</td>
<td>1000ft vertical 1500m horizontal ≤3000’ ≤1000AGL clear of cloud</td>
</tr>
<tr>
<td>E</td>
<td>Yes</td>
<td>Continuous two way</td>
<td>No</td>
<td>Info only</td>
<td>5000m^</td>
<td>1000ft vertical 1500m horizontal</td>
</tr>
<tr>
<td>D</td>
<td>No</td>
<td>Continuous two way</td>
<td>2-way comms</td>
<td>Info only</td>
<td>5000m^</td>
<td>1000’ above cloud 500’ below cloud 600m horizontal</td>
</tr>
<tr>
<td>C</td>
<td>Yes</td>
<td>Continuous two way</td>
<td>Yes</td>
<td>Info from VFR Sep. from IFR SVFR from SVFR*</td>
<td>5000m^</td>
<td>1000ft vertical 1500m horizontal</td>
</tr>
<tr>
<td>A</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>-</td>
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</tbody>
</table>

^Visibility always 8000m above 10,000’
*Special VFR clearance: Visibility 1600m, Clear of cloud. Must see ground/water when below 2000’ AGL.
### IFR FLIGHTS

<table>
<thead>
<tr>
<th>FLIGHTS</th>
<th>XPDR</th>
<th>SERVICE</th>
<th>CLEARANCE</th>
<th>SEPARATION</th>
</tr>
</thead>
<tbody>
<tr>
<td>G</td>
<td>Yes, ADS-B reqd.</td>
<td>FIS</td>
<td>No</td>
<td>Info only</td>
</tr>
<tr>
<td>E</td>
<td><em>IFR flight without discrete transponder code assigned:</em> OCTA sqawk 2000 CTA/CTR sqawk 3000.</td>
<td>ATC</td>
<td>Yes</td>
<td>From IFR and from SVFR</td>
</tr>
<tr>
<td>D</td>
<td></td>
<td></td>
<td>Yes</td>
<td>From all aircraft</td>
</tr>
<tr>
<td>C</td>
<td></td>
<td></td>
<td>Yes</td>
<td>Info only</td>
</tr>
<tr>
<td>A</td>
<td></td>
<td></td>
<td>Yes</td>
<td>Info only</td>
</tr>
</tbody>
</table>

Speed restriction is 250kt below 10,000’. Class D for all aircraft: 200kt ≤ 2500’ AAL and within 4NM.

### 16. RVSM AIRSPACE GEN 1.5 p9, PART 91 MOS 11.07

RVSM airspace is Class A airspace between FL 290 and FL 410 inclusive where ATC may separate aircraft by minimum of 1,000ft vertically. Only CASA approved operators may operate with RVSM within this airspace.

### 17. VECTORS ENR 1.6 p3, ENR 1.7 p4

Change of level must be commenced asap but no later than 1 minute of receiving instruction.

Change of heading must be commenced immediately (rate 1 turn or 25° whichever is less).

When being vectored on headings that could infringe terrain clearance of separation standards, the interval between ATC transmissions will not exceed 30 seconds.

### 18. CAT/SPEEDS ENR 1.5 p1.15, PART 91 MOS 2.02

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<tr>
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<tbody>
<tr>
<td>Vat</td>
<td>Initial</td>
<td>Final</td>
<td>Circling</td>
<td>MAP</td>
</tr>
<tr>
<td>Cat A</td>
<td>&lt;91</td>
<td>90-150</td>
<td>70-100</td>
<td>&lt;100</td>
</tr>
<tr>
<td>Cat B</td>
<td>91-120</td>
<td>120-180</td>
<td>85-130</td>
<td>&lt;135</td>
</tr>
<tr>
<td>Cat C</td>
<td>121-140</td>
<td>160-240</td>
<td>115-160</td>
<td>&lt;180</td>
</tr>
</tbody>
</table>

Holding up to FL140: 230kt, or 170kt where approach is limited to Cat A/B only.

Holding above FL140 up to and including FL200: 240kt. Holding above FL200: 265kt.

### 19. CAPTURE REGIONS ENR 1.5 p2.4, ENR 1.5 p3.4, ENR 1.5 p3

Sector entry defined by arrival HEADING. S1 Parallel, S2 Offset, S3 Direct. Can choose sector entry if heading within 5° of boundary line.

Reversal approaches: Can go straight in to approach if enroute arrival track is within 30° of outbound track. When the 30° direct entry sector does not include the reciprocal of the inbound track, the entry sector is expanded to include it.

For RNAV approach: 70° each side of the track for the “centre” IAF, or for other IAF, if outside the line parallel to final track.

### 20. APPROACHES GEN 2.2, ENR 1.5 p1.83, ENR 1.5 p2.7.3

Δ symbol means IAF.

钯 symbol means FAF for 2D approaches and FAP for 3D approaches.

Reversal approaches don’t show钯 on chart, but the FAF is taken to be when established inbound on appr.

For a reversal approach, descent on the OB leg may commence when established on track, or turned onto a heading to intercept the OB track. Descent on the IB leg may only commence once established on the IB track.

Straight-in instrument approaches can be offset by up to 30° of RWY centreline (15° for Cat C & D).

### 21. APPROACH BAN PART 91 MOS 16.01

The pilot in command must not descend below 1 000 ft AAE where the TDZ RVR is reported by ATC as continually less than the landing minima for the IAP.

However, if after passing 1 000 ft AAE, the TDZ RVR is reported by ATC as falling below the landing minima, the approach may be continued.
22. LANDING MINIMA P91 MOS 14.03

TAF QNH: MDA/DA as printed on chart.
Shaded box: Reduce MDA/DA by 100ft with “Actual QNH” (ATIS, AWIS, ATC, MET observer), QNH valid 15min.
Using Area QNH (Area forecast QNH): Increase MDA/DA by 50ft.
Temperature colder than ISA-15°C, altitude correction as per DAP 2-2 and 2-3 (instructions DAP 1-1 p1.5).
For ILS approach, add 50ft to DA if not using aircraft PEC.

ILS/LOC OR RNP3D PART 91 MOS 15.10

ILS if no glide slope, continue with LLZ approach (can switch prior to FAP).
For LLZ approach if HIAL not avlb increase Vis by 900m.

ILS CAT 1 or RNP3D Visibility shall be the higher of the visibility printed on approach chart or:
Vis 0.8Km when instrumented RVR not available
Vis 1.2Km unless: Coupled autopilot, FD, or HUD, failure warning system for AH/DI, HIREL available
Vis 1.5Km when HIAL is not available

AIP ENR 1.1 p10.7.4.8: At a controlled aerodrome with interleaved circuitry lighting, if one runway lighting circuit fails, light spacing 60m > 120m. Increase minimum visibility for procedure by x1.5 unless in VMC.

23. EXECUTE MISSED APPROACH PART 91 MOS 15.11

Straight in landing not possible and circling approach not possible
Not Visual at MAPT or DA
RAIM failure or warning after IAF
Outside tolerance past FAF
Failure of navaid, or suspicious navaid
Loss of visual reference during circling

24. FLIGHT BELOW LSALT GEN 3.3 p4.4

MSA
DME/GNSS arrival
Instrument approach or holding
Vectors
VMC by day
Visual approach
Climb after takeoff

25. VISUAL CIRCLING (DESCENT BELOW MDA) ENR 1.5 p1.7, ENR 1.10 p1.4, ENR 1.5 p1.8

Maintain aircraft in circling area
Visibility (as per approach chart) along the intended flight path
Maintain visual contact with landing runway environment (threshold, lights, etc)
By day:
Maintain visual contact with obstacles along the intended flight path
Maintain not less than 300’ abv obstacles (Cat A/B) along intended flight path until aligned with runway on final
By night:
Can’t descend below MDA until MDA intercepts normal circuit descent profile on downwind, base or final.
VISUAL APPROACH ENR 1.1 p2.11.3, ENR 1.5 p1.15

By day: Within 30NM, from not below the LSALT/MSA/MDA
Clear of cloud
In sight of ground or water
Vis 5000m
Can maintain minimum altitude as per CASR 91.265/91.267 (old CAR 157) to the circling area

Controlled airspace:
Clear of cloud, Vis 5000m, can maintain continuous visual reference to ground or water to aerodrome
Descend not below CTA LL +500’ and not below CAR157.
Maintain last cleared track/heading until within 5NM (or circling area at night), then manoeuvre for landing runway. If on a STAR and subsequently cleared for visual approach, follow STAR lateral profile, including any visual or instrument termination route.

By night:
Clear of cloud
In sight of ground or water
Vis 5000m
Not below the LSALT/MSA/MDA until the circling area (or 3NM if AD with no instrument app), or:
Within 5NM (7NM if ILS runway) of aerodrome, established not below T-VASIS or PAPI, aligned with runway
Within 10NM if established not below ILS GS and less than full scale deflection of LOC

26. USE OF GNSS AS SUBSTITUTE FOR GROUND NAV AIDS PART 91 MOS 14.05

GNSS may be used as a substitute to a ground-based navaid for NDB, VOR, DME, and OM/MM.
This includes for tracking during NDB and VOR approaches, as well as for distance information during an ILS/LLZ or GNSS arrival. This does not include for tracking during a DME/GNSS Arrival.

If a GNSS is used to substitute a ground-based navaid for NDB or VOR, the IAP must be loaded into the GNSS receiver to ensure the receiver will transition to RNP APCH with CDI sensitivity of ≤0.3NM by the FAF.

27. ICING NASA (link)

Two conditions required for ice to form: visible moisture and temperature below 0°C.

Clear ice: Large water droplets or freezing rain strike the leading edge and do not freeze instantly but rather flow aft along the aerofoil before freezing. Visually, it appears as a transparent, often invisible layer of ice on the aerofoil. Apart from changing the shape of the aerofoil, it can add enormous weight to the aeroplane, both of which increase stall speed. Most likely to occur at temperatures 0° to -15°.

Rime ice: Small supercooled water droplets instantly freeze on impact. Rough and opaque white appearance on the aerofoil leading edge. Severely disturbs airflow, degrading performance and increasing stall speed. Most likely to occur at temperatures -10° to -25°.

Mixed ice: A combination of Clear ice and Rime ice. Most likely to form at temperatures -10° to -15°.

Due to temperature variations at the low pressure areas on the aerofoil, as well as a potential inaccuracy of the OAT gauge, consider icing conditions as possible any time OAT falls below 3°C.

To exit icing conditions encountered in stratiform clouds, change altitude by at least 3000’ up or down.
To exit icing conditions in cumuliform clouds, divert laterally and vertically to exit clouds.
Plan to cross cold fronts on a perpendicular track to shorten the duration of the potential icing encounter.
28. COMMUNICATIONS FAILURE ERSA EMERG 1.5, PART 91 MOS 11.10

a. Squawk 7600
b. Listen out on ATIS and/or voice modulated NAVAIDs.
c. Transmit intentions and make normal position reports (prefix calls with “TRANSMITTING BLIND”).

AND

if in VMC and are certain of maintaining VMC

a. Stay in VMC and land at the most suitable aerodrome (note special procedures if proceeding to a Class D).

OR

If in IMC or are uncertain of maintaining VMC

b. If no clearance limit received and acknowledged, proceed in accordance with the latest ATC route clearance acknowledged and climb to planned level.
c. If a clearance limit involving an altitude or route restriction has been received and acknowledged:
   i. maintain last assigned level, or MSA if higher, for three minutes and/or
   ii. hold at nominated location for three minutes, then
   iii. proceed in accordance with the latest ATC route clearance acknowledged and climb to planned level.

d. If receiving an ATS surveillance service:
   i. climb to MSA/LSALT, and,
   ii. if being vectored, maintain last assigned vector for two minutes, then
   iii. proceed in accordance with the latest ATC route clearance acknowledged.
e. If holding:
   i. fly one more complete holding pattern, then
   ii. proceed in accordance with the latest ATC route clearance acknowledged.

Destination Procedures:

a. Track to the destination in accordance with flight plan (amended by the latest ATC clearance acknowledged, if applicable).
b. Commence descent in accordance with standard operating procedures or flight plan.
c. Descend to the initial approach altitude for the most suitable approach aid in accordance with the published procedures.
d. Carry out the approach to the prescribed minima (and if the tower is open, look for light signals)

29. PERFORMANCE CAO 20.7.4, PART 91 MOS 10.09

Takeoff & Landing distances: Multiply by a factor of 1.15 for aeroplanes below 2000kg unless the performance charts already include it. Between 2000kg and 4500kg, linear interpolation between 1.15 and 1.43.

Climb gradients:

Takeoff configuration (with gear down at Vtoss): 6%
Landing climb performance (ie go-around config, at 1.3 Vs): 3.2%

Enroute climb at 4.5% up to 5000’ for single engine aircraft only

IFR AWK and Charter: With OEI ability to climb at 1% up to 5000’
VFR, PVT IFR: With OEI ability to maintain height at all altitudes up to 5000

In the case of an engine failure after takeoff, the PIC must have a plan to return to land or proceed to a takeoff alternate, whilst remaining clear of obstacles. If any drift-down procedures are planned, the aeroplane must remain clear of obstacles by 2000ft within 5NM of track until established in the circuit area.
30. CALCULATION OF LSALT  AIP GEN 3.3 p4

RNP2: Highest obstacle within 5NM either side of track +1000’ or +1360’ (see below).
NVFR: Highest obstacle within 10NM either side of track +1000’ or +1360’ (see below).
A LSALT can never be lower than 1500’.

Note: It’s not enough to just look for spot heights. Hypsometric tinting must also be carefully analysed.
For example, terrain may gradually rise towards a spot height that falls just outside the area of consideration.

31. MULTI-ENGINE NOTES

Vmca: The IAS below which it’s not possible to maintain directional control of the aeroplane with OEI. Marked with a red line on the ASI.

Vmca is a speed that depends on the aeroplane configuration (just like Vs does) and it’s measured in the following conditions:
- critical engine inoperative
- live engine at take-off power
- landing gear retracted
- maximum of 5 degrees bank towards live engine
- propeller windmilling (for aircraft with auto-feather, propeller feathered)

Recovery: close both throttles, pitch down, then smoothly re-apply power whilst pitching up to maintain Vyse.

Critical Engine: The engine whose failure will have the most detrimental effect on control and performance. For clockwise rotating props, the LH engine is critical. For counter-rotating props (BE76, PA44) there is no critical engine.

32. RAISING THE MDA

You must be able to clear obstacles in the MAP even if you suffer an engine failure. The standard 2.5% MAP gradient only ensures 100ft obstacle clearance, so you definitely need to ensure you’ll achieve at least 2.5%.
If you can’t, the MDA (or DA) must be raised in accordance with your “shortfall”.

\[
\text{Shortfall to be added to the MDA} = (\text{MSA} - \text{MDA}) - ((\text{MSA} - \text{MDA}) \times \frac{\text{OEI gradient}}{2.5})
\]

If the AFM gives a rate of climb but not a gradient, use table DAP 2-1 or this approximation  \(ROC = GS \times GR(\%)\)

33. GENERAL FORMULAS

\[
PNR = \frac{SE \times \text{GSH}}{GSO + \text{GSH}} = \text{minutes}
\]

\[
CP/ETP = \frac{\text{DIST} \times \text{GSH}}{GSO + \text{GSH}} = \text{miles}
\]

\[
AOB (R1 \text{ turn}) = \frac{\text{IAS} + \text{half the result}}{10}
\]
34. FLIGHT TEST STANDARDS MOS SCHEDULE 4 Table 2, Table 5
PBN/RNP ENR 1.10 ITEM 10, ENR 1.1 p4.2.7

PBN: Performance Based Navigation. The concept by which the different navigational capabilities are defined.
RNP: Required Navigation Performance. It defines what level of accuracy the aircraft’s navigation system is expected to perform to. For the purposes of GA within continental Australia, the following RNP are defined:
- **RNP2 (RNP ENR)** full scale CDI deflection is 2NM, and is used in the cruise phase of flight.
- **RNP1 (RNP TERM)** full scale CDI deflection is 1NM, and is used within 30NM of departure & destination AD.
- **RNP0.3 (RNP APCH)** is used for IAP. Transition from TERM to APCH is completed before the FAF.

**GNSS Principles:**
- 4 Satellites required for 3D navigation solution
- 5 Satellites required for FD (Fault Detection)(TSO C129 certified GPS)
- 6 Satellites required for FDE (Fault Detection and Exclusion)(TSO C145/C146 certified GPS)

**RAIM Failure:** RAIM not available ie. less than 5 satellites in range ["INTEG" message]

**RAIM Position Warning:** Unresolved discrepancy ["WARN"], CDI will be automatically disabled.

**RNAV Approach:** Past the FAF, RAIM failure messages are inhibited (for up to 5 minutes), ie if there are only 4 satellites the unit will continue to operate as normal even though FD is unavailable. However if the GPS can’t determine the position or there is an unresolved discrepancy, a Position Warning will still be displayed, the CDI disabled, and a missed approach must be initiated.

**ADS-B** stands for “Automatic Dependant Surveillance Broadcast”. Traditionally transponders waited to be interrogated by a radar station and then replied with very simple data that consisted of a 4 digit transponder code (Mode A), a barometric altitude (Mode C), and more recently the aircraft’s callsign (Mode S). The interrogating station then had to figure out 1) which direction the signal came from and 2) how long it took for the signal to do the round trip. With all that information (including the reported altitude) it could then determine the aeroplane’s relative position and plot its coordinates.

**ADS-B** transponders require a GPS input and send the aircraft’s real-time coordinates to the interrogating station (as well as a transponder code, altitude, rate of climb/descent, track, groundspeed, callsign, etc.). These GPS coordinates are still received by dedicated ground stations but are orders of magnitude more accurate than traditional radar-transponder systems. The ground stations are also simpler/cheaper to run which is why they have been deployed throughout Australia, covering most of the country.

There are different types of **ADS-B** transponder. **ADS-B OUT** transponder broadcasts data every half second. The **ADS-B IN** function is optional and is used in conjunction with TCAS systems to display the position of other aircraft to the pilots.

Most GA aeroplanes only have 1090MHz **ADS-B OUT** and will therefore select **E B1** on the flight notification.